

11. (Amended) A method of inputting at a near terminal a representation of a body and coordinates of a reference point and transmitting these to a remote terminal running a program for executing the method of claim 1, and receiving at a near location an output of any of the methods.

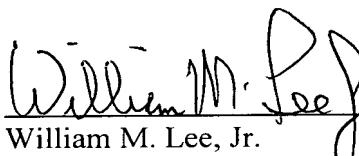
15. (Amended) The computer system according to claim 13, wherein the Wave Transfer Vector is an Acoustic Transfer Vector, further comprising: means for computing a Modal Acoustic Transfer Vector (MATV) from an acoustic transfer vector (ATV) in an alternative coordinate system defined by a set of deformed shapes by a body by projecting the ATV into the modal space.

REMARKS

The above amendments are being made in order to eliminate multiple dependency before calculation of the application filing fee.

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Respectfully submitted,



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Version with Markings to Show Changes Made

9. (Amended) A processing engine adapted to carry out [any of] the [methods] method of claim 1 [to 8].

10. (Amended) A computer program product for executing on a computer, the computer program product executing any of the method steps of claim 1 [to 8] when executed on the computer.

11. (Amended) A method of inputting at a near terminal a representation of a body and coordinates of a reference point and transmitting these to a remote terminal running a program for executing [any of] the [methods] method of claim 1 [to 8], and receiving at a near location an output of any of the methods.

15. (Amended) The computer system according to claim 13 [or 14], wherein the Wave Transfer Vector is an Acoustic Transfer Vector, further comprising: means for computing a Modal Acoustic Transfer Vector (MATV) from an acoustic transfer vector (ATV) in an alternative coordinate system defined by a set of deformed shapes by a body by projecting the ATV into the modal space.